

Curvature Tensor of the Stationary Accelerated Frame in Gravity Field

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We define an accelerated frame that moves along \hat{r} -axis in the general relativistic curved space-time. We then calculate the curvature tensor of this accelerated frame in the stationary gravity field. The curvature tensor is divided into two parts: the curvature tensor as observed by the observer and the curvature tensor of the observer's own planet in the gravity field.

1. Introduction

The objective at first is to define an accelerated frame that moves along \hat{r} -axis in the curved space-time. In this context, the Schwarzschild solution is given as

$$\begin{aligned} d\tau^2 &= \left(1 - \frac{2GM}{rc^2}\right) dt^2 \\ &\quad - \frac{1}{c^2} \left[\frac{dr^2}{1 - \frac{2GM}{rc^2}} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \right] \end{aligned} \quad (1)$$

Now, the acceleration of moving matter is a in the Schwarzschild space-time, which is given as

$$a = \frac{d}{dt} \left(\frac{u}{\sqrt{1 - \frac{2GM}{rc^2} - \frac{u^2}{c^2}}} \right) = a_{\text{inertial}} - g$$

Here, a_{inertial} is the inertial acceleration, g is the pure gravity acceleration and u is given as

$$u = \frac{1}{\sqrt{1 - \frac{2GM}{rc^2}}} \frac{dr}{dt} \quad (2)$$

If $a_0 = a / \sqrt{1 - \frac{2GM}{rc^2}}$ then

$$\begin{aligned} a_0 &= \frac{1}{\sqrt{1 - \frac{2GM}{rc^2}}} \frac{d}{dt} \left(\frac{u}{\sqrt{1 - \frac{2GM}{rc^2} - \frac{u^2}{c^2}}} \right) = \frac{d}{d\hat{t}} \left(\frac{V}{\sqrt{1 - \frac{V^2}{c^2}}} \right) \\ V &= \frac{d\hat{r}}{d\hat{t}} = \frac{dr}{dt} \frac{1}{\left(1 - \frac{2GM}{rc^2}\right)}, \quad d\hat{t} = dt \sqrt{1 - \frac{2GM}{rc^2}}, \\ d\hat{r} &= \frac{dr}{\sqrt{1 - \frac{2GM}{rc^2}}} \\ a_0 \hat{t} &= \frac{V}{\sqrt{1 - \frac{V^2}{c^2}}}, \quad V = \frac{a_0 \hat{t}}{\sqrt{1 + \frac{a_0^2 \hat{t}^2}{c^2}}}, \end{aligned} \quad (3)$$

Here, V is the velocity of \hat{r} -axis velocity

If $\frac{d\theta}{dt} = \frac{d\phi}{dt} = 0$, the solution is

$$\begin{aligned} d\tau^2 &= \left(1 - \frac{2GM}{rc^2}\right) dt^2 - \frac{1}{c^2} \frac{dr^2}{1 - \frac{2GM}{rc^2}} = d\hat{t}^2 \\ - \frac{1}{c^2} d\hat{r}^2 &= d\hat{t}^2 \left(1 - \frac{V^2}{c^2}\right) \end{aligned} \quad (4)$$

Now,

$$\begin{aligned} \tau &= \int d\tau = \int \frac{d\hat{t}}{\sqrt{1 + \frac{a_0^2 \hat{t}^2}{c^2}}} = \frac{c}{a_0} \sinh^{-1} \left(\frac{a_0}{c} \hat{t} \right), \\ \hat{t} &= \frac{c}{a_0} \sinh \left(\frac{a_0 \tau}{c} \right), \end{aligned}$$

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$$\begin{aligned}\hat{r} &= \int V d\hat{t} = \int \frac{a_0 \hat{t} d\hat{t}}{\sqrt{1 + \frac{a_0^2 \hat{t}^2}{c^2}}} = \frac{c^2}{a_0} \sqrt{1 + \frac{a_0^2 \hat{t}^2}{c^2}} \\ &= \frac{c^2}{a_0} \cosh\left(\frac{a_0 \tau}{c}\right) \\ \frac{d\hat{t}}{d\tau} &= \cosh\left(\frac{a_0}{c} \tau\right), \quad \frac{1}{c} \frac{d\hat{r}}{d\tau} = \sinh\left(\frac{a_0}{c} \tau\right)\end{aligned}\quad (5)$$

2. The Tetrad in Curved Space-time

The tetrad $e^{\hat{\alpha}}_{\hat{\mu}}$ is the unit vector, which is defined by the following formula

$$\eta_{\hat{\alpha}\hat{\beta}} e^{\hat{\alpha}}_{\hat{\mu}} e^{\hat{\beta}}_{\hat{\nu}} = g_{\hat{\mu}\hat{\nu}} \quad (6)$$

Now, if the matter moves along \hat{r} -axis in the curved space-time

$$\eta_{\hat{\alpha}\hat{\beta}} e^{\hat{\alpha}}_{\hat{\mu}}(\tau) e^{\hat{\beta}}_{\hat{\nu}}(\tau) = g_{\hat{\mu}\hat{\nu}} = \eta_{\hat{\mu}\hat{\nu}}, \quad g_{\hat{\mu}\hat{\nu}} = \eta_{\hat{\mu}\hat{\nu}} \quad (7)$$

Hence, Eqn. (6), Eqn. (7) become

$$\eta_{\hat{\alpha}\hat{\beta}} e^{\hat{\alpha}}_{\hat{0}}(\tau) e^{\hat{\beta}}_{\hat{0}}(\tau) = \eta_{\hat{0}\hat{0}} = -1 \quad (8)$$

$$\begin{aligned}d\tau^2 &= -\frac{1}{c^2} \eta_{\hat{\alpha}\hat{\beta}} d\hat{x}^\alpha d\hat{x}^\beta \\ \rightarrow -1 &= \eta_{\hat{\alpha}\hat{\beta}} \left(\frac{1}{c} \frac{d\hat{x}^\alpha}{d\tau}\right) \left(\frac{1}{c} \frac{d\hat{x}^\beta}{d\tau}\right) = \eta_{\hat{\alpha}\hat{\beta}} e^{\hat{\alpha}}_{\hat{0}}(\tau) e^{\hat{\beta}}_{\hat{0}}(\tau) \\ \hat{x}^\alpha &= (ct, \hat{r}, \hat{\theta}, \hat{\phi})\end{aligned}\quad (9)$$

According to Eqn. (5) and Eqn. (9),

$$e^{\hat{\alpha}}_{\hat{0}}(\tau) = \frac{1}{c} \frac{d\hat{x}^\alpha}{d\tau} = (\cosh\left(\frac{a_0 \tau}{c}\right), \sinh\left(\frac{a_0 \tau}{c}\right), 0, 0) \quad (10)$$

About $\hat{\theta}$ -axis and $\hat{\phi}$ -axis orientations, as

$$\begin{aligned}\eta_{\hat{2}\hat{2}} e^{\hat{2}}_{\hat{2}}(\tau) e^{\hat{2}}_{\hat{2}}(\tau) &= \eta_{\hat{2}\hat{2}} = 1, \quad e^{\hat{\alpha}}_{\hat{2}}(\tau) = (0, 0, 1, 0) \\ \eta_{\hat{3}\hat{3}} e^{\hat{3}}_{\hat{3}}(\tau) e^{\hat{3}}_{\hat{3}}(\tau) &= \eta_{\hat{3}\hat{3}} = 1, \quad e^{\hat{\alpha}}_{\hat{3}}(\tau) = (0, 0, 0, 1)\end{aligned}\quad (11)$$

The other vector, $e^{\hat{\alpha}}_{\hat{1}}(\tau)$ has to satisfy the tetrad condition given by Eqn. (6) and Eqn. (7), and therefore we have

$$e^{\hat{\alpha}}_{\hat{1}}(\tau) = (\sinh\left(\frac{a_0 \tau}{c}\right), \cosh\left(\frac{a_0 \tau}{c}\right), 0, 0) \quad (12)$$

Now, since

$$\begin{aligned}\bar{e}_{\hat{t}}^{\hat{\rho}} &= (1/\sqrt{1 - \frac{2GM}{rc^2}}, 0, 0, 0) \\ \bar{e}_{\hat{r}}^{\hat{\rho}} &= (0, \sqrt{1 - \frac{2GM}{rc^2}}, 0, 0) \\ \bar{e}_{\hat{\theta}}^{\hat{\rho}} &= (0, 0, 1/r, 0), \quad \bar{e}_{\hat{\phi}}^{\hat{\rho}} = (0, 0, 0, 1/r \sin \theta) \\ g_{\rho\sigma} \bar{e}_{\hat{\alpha}}^{\hat{\rho}} \bar{e}_{\hat{\beta}}^{\hat{\sigma}} &= \eta_{\hat{\alpha}\hat{\beta}}\end{aligned}\quad (13)$$

$$\begin{aligned}\frac{a_0}{c} \hat{t} &= \sinh\left(\frac{a_0}{c} \tau\right) = \frac{v/c}{\sqrt{1-v^2/c^2}}, \\ \sqrt{1 + \frac{a_0^2 \hat{t}^2}{c^2}} &= \cosh\left(\frac{a_0}{c} \tau\right) = \frac{1}{\sqrt{1-v^2/c^2}}\end{aligned}\quad (14)$$

Therefore, the Lorentz transformation $B^{\hat{\alpha}}_{\hat{\mu}}(v)$ is

$$\begin{aligned}B^{\hat{\alpha}}_{\hat{\mu}}(v) &= \begin{pmatrix} 1 & \frac{v/c}{\sqrt{1-v^2/c^2}} & 0 & 0 \\ \frac{v/c}{\sqrt{1-v^2/c^2}} & \frac{1}{\sqrt{1-v^2/c^2}} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ &= e^{\hat{\alpha}}_{\hat{\mu}}(\tau) = \begin{pmatrix} \cosh\left(\frac{a_0}{c} \tau\right) & \sinh\left(\frac{a_0}{c} \tau\right) & 0 & 0 \\ \sinh\left(\frac{a_0}{c} \tau\right) & \cosh\left(\frac{a_0}{c} \tau\right) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}\end{aligned}\quad (15)$$

$$\bar{e}'_{\hat{\mu}}^{\hat{\rho}} = B^{\hat{\alpha}}_{\hat{\mu}}(v) \bar{e}_{\hat{\alpha}}^{\hat{\rho}} = e^{\hat{\alpha}}_{\hat{\mu}}(\tau) \bar{e}_{\hat{\alpha}}^{\hat{\rho}} \quad (16)$$

Hence,

$$\begin{aligned}g_{\rho\sigma} \bar{e}_{\hat{\alpha}}^{\hat{\rho}} \bar{e}_{\hat{\beta}}^{\hat{\sigma}} &= \eta_{\hat{\alpha}\hat{\beta}} \\ g_{\rho\sigma} B^{\hat{\alpha}}_{\hat{\mu}}(v) \bar{e}_{\hat{\alpha}}^{\hat{\rho}} B^{\hat{\beta}}_{\hat{\nu}}(v) \bar{e}_{\hat{\beta}}^{\hat{\sigma}} &= g_{\rho\sigma} \bar{e}'_{\hat{\mu}}^{\hat{\rho}} \bar{e}'_{\hat{\nu}}^{\hat{\sigma}} = \eta_{\hat{\mu}\hat{\nu}}\end{aligned}\quad (17)$$

3. The Accelerated Frame in the Curved Space-time

The accelerated frame $\hat{\xi}$ in the curved space-time can be defined as

$$\begin{aligned} d\tau^2 &= -\frac{1}{c^2} \eta_{\hat{\alpha}\hat{\beta}} d\hat{x}^\alpha d\hat{x}^\beta = -\frac{1}{c^2} \eta_{\hat{\alpha}\hat{\beta}} \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^\mu} \frac{\partial \hat{x}^\beta}{\partial \hat{\xi}^\nu} d\hat{\xi}^\mu d\hat{\xi}^\nu \\ &= -\frac{1}{c^2} \eta_{\hat{\alpha}\hat{\beta}} e^{\hat{\alpha}}{}_{\hat{\mu}} e^{\hat{\beta}}{}_{\hat{\nu}} d\hat{\xi}^\mu d\hat{\xi}^\nu \\ &= -\frac{1}{c^2} g_{\hat{\mu}\hat{\nu}} d\hat{\xi}^\mu d\hat{\xi}^\nu \end{aligned} \quad (18)$$

$$e^{\hat{\alpha}}{}_{\hat{\mu}} = \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^\mu}, \quad \frac{\partial e^{\hat{\alpha}}{}_{\hat{\mu}}}{\partial \hat{\xi}^1} = \frac{\partial^2 \hat{x}^\alpha}{c \partial \hat{\xi}^0 \partial \hat{\xi}^1} = \frac{\partial e^{\hat{\alpha}}{}_{\hat{1}}}{c \partial \hat{\xi}^0} \quad (19)$$

3.1. Case-1

Now, in Eqns. (10) - (12), if one uses $\hat{\xi}^0$ instead of τ , then one can obtain new equations as

$$\begin{aligned} e^{\hat{\alpha}}{}_{\hat{0}}(\hat{\xi}^0) &= \frac{1}{c} \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^0} = ((1 + \frac{a_0 \hat{\xi}^1}{c^2}) \cosh(\frac{a_0 \hat{\xi}^0}{c}), \\ &\quad (1 + \frac{a_0 \hat{\xi}^1}{c^2}) \sinh(\frac{a_0 \hat{\xi}^0}{c}), 0, 0) \end{aligned} \quad (20)$$

$$e^{\hat{\alpha}}{}_{\hat{1}}(\hat{\xi}^0) = \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^1} = (\sinh(\frac{a_0 \hat{\xi}^0}{c}), \cosh(\frac{a_0 \hat{\xi}^0}{c}), 0, 0) \quad (21)$$

$$\begin{aligned} e^{\hat{\alpha}}{}_{\hat{2}}(\hat{\xi}^0) &= \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^2} = (0, 0, 1, 0), \\ e^{\hat{\alpha}}{}_{\hat{3}}(\hat{\xi}^0) &= \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^3} = (0, 0, 1, 0) \end{aligned} \quad (22)$$

$$\begin{aligned} d\hat{x}^\alpha &= \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^\mu} d\hat{\xi}^\mu = e^{\hat{\alpha}}{}_{\hat{0}}(\hat{\xi}^0) c d\hat{\xi}^0 + e^{\hat{\alpha}}{}_{\hat{1}}(\hat{\xi}^0) d\hat{\xi}^1 \\ &\quad + e^{\hat{\alpha}}{}_{\hat{2}}(\hat{\xi}^0) d\hat{\xi}^2 + e^{\hat{\alpha}}{}_{\hat{3}}(\hat{\xi}^0) d\hat{\xi}^3 \end{aligned} \quad (23)$$

Hence,

$$\begin{aligned} c d\hat{t} &= c dt \sqrt{1 - \frac{2GM}{rc^2}} = (1 + \frac{a_0 \hat{\xi}^1}{c^2}) \cosh(\frac{a_0 \hat{\xi}^0}{c}) c d\hat{\xi}^0 \\ &\quad + \sinh(\frac{a_0 \hat{\xi}^0}{c}) d\hat{\xi}^1 \end{aligned}$$

$$\begin{aligned} d\hat{r} &= \frac{dr}{\sqrt{1 - \frac{2GM}{rc^2}}} = (1 + \frac{a_0 \hat{\xi}^1}{c^2}) \sinh(\frac{a_0 \hat{\xi}^0}{c}) c d\hat{\xi}^0 \\ &\quad + \cosh(\frac{a_0 \hat{\xi}^0}{c}) d\hat{\xi}^1 \\ d\hat{\theta} &= d\hat{\xi}^2, \quad d\hat{\phi} = d\hat{\xi}^3 \end{aligned} \quad (24)$$

$$\begin{aligned} d\tau^2 &= (1 - \frac{2GM}{rc^2}) dt^2 - \frac{1}{c^2} [\frac{dr^2}{1 - \frac{2GM}{rc^2}} + r^2 d\theta^2 \\ &\quad + r^2 \sin^2 \theta d\phi^2] \\ &= d\hat{t}^2 - \frac{1}{c^2} [d\hat{r}^2 + d\hat{\theta}^2 + d\hat{\phi}^2] \\ &= (1 + \frac{a_0 \hat{\xi}^1}{c^2})^2 (d\hat{\xi}^0)^2 - \frac{1}{c^2} [(d\hat{\xi}^1)^2 + (d\hat{\xi}^2)^2 + (d\hat{\xi}^3)^2] \end{aligned} \quad (25)$$

The co-ordinate transformation is

$$\begin{aligned} \hat{ct} &= (\frac{c^2}{a_0} + \hat{\xi}^1) \sinh(\frac{a_0 \hat{\xi}^0}{c}), \\ \hat{r} &= (\frac{c^2}{a_0} + \hat{\xi}^1) \cosh(\frac{a_0 \hat{\xi}^0}{c}) - \frac{c^2}{a_0} \\ \hat{\theta} &= \hat{\xi}^2, \quad \hat{\phi} = \hat{\xi}^3 \end{aligned} \quad (26)$$

The inverse-transformation is

$$\begin{aligned} \hat{\xi}^0 &= \frac{c}{a_0} \tanh^{-1} \left(\frac{c \hat{t}}{\hat{r} + \frac{c^2}{a_0}} \right), \\ \hat{\xi}^1 &= \sqrt{(\hat{r} + \frac{c^2}{a_0})^2 - c^2 \hat{t}^2} - \frac{c^2}{a_0} \\ \hat{\xi}^2 &= \hat{\theta}, \quad \hat{\xi}^3 = \hat{\phi} \end{aligned} \quad (27)$$

We now calculate the curvature tensor $R_{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\lambda}}(\hat{\xi})$ thus obtaining the following expression

$$\begin{aligned}
R_{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\lambda}}(\hat{\xi}) &= \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^\mu} \frac{\partial \hat{x}^\beta}{\partial \hat{\xi}^\nu} \frac{\partial \hat{x}^\gamma}{\partial \hat{\xi}^\rho} \frac{\partial \hat{x}^\delta}{\partial \hat{\xi}^\lambda} R_{\hat{\alpha}\hat{\beta}\hat{\gamma}\hat{\delta}}(\hat{X}) \\
&= e^{\hat{\alpha}_{\hat{\mu}}}(\hat{\xi}^0) e^{\hat{\beta}_{\hat{\nu}}}(\hat{\xi}^0) e^{\hat{\gamma}_{\hat{\rho}}}(\hat{\xi}^0) e^{\hat{\delta}_{\hat{\lambda}}}(\hat{\xi}^0) R_{\hat{\alpha}\hat{\beta}\hat{\gamma}\hat{\delta}}(\hat{X})
\end{aligned} \tag{28}$$

$R_{\hat{r}\hat{r}\hat{r}\hat{r}} = -R_{\hat{r}\hat{r}\hat{r}\hat{r}} = R_{\hat{r}\hat{r}\hat{r}\hat{r}} = -R_{\hat{r}\hat{r}\hat{r}\hat{r}} = \frac{2GM}{r^3 c^2}$,

$$\begin{aligned}
R_{\hat{i}\hat{\theta}\hat{\theta}} &= -R_{\hat{i}\hat{\theta}\hat{\theta}} = R_{\hat{\theta}\hat{\theta}\hat{\theta}} = -R_{\hat{\theta}\hat{i}\hat{\theta}} = -\frac{GM}{r^3 c^2} = R_{\hat{i}\hat{\phi}\hat{\phi}} \\
&= -R_{\hat{i}\hat{\phi}\hat{\phi}} = R_{\hat{\phi}\hat{\phi}\hat{\phi}} = -R_{\hat{\phi}\hat{i}\hat{\phi}}
\end{aligned}$$

$$\begin{aligned}
R_{\hat{\theta}\hat{\theta}\hat{\theta}\hat{\theta}} &= -R_{\hat{\theta}\hat{\theta}\hat{\theta}\hat{\theta}} = R_{\hat{\theta}\hat{\theta}\hat{\theta}\hat{\theta}} = -R_{\hat{\theta}\hat{\theta}\hat{\theta}\hat{\theta}} = -\frac{2GM}{r^3 c^2} \\
R_{\hat{r}\hat{\theta}\hat{\theta}\hat{\theta}} &= -R_{\hat{r}\hat{\theta}\hat{\theta}\hat{\theta}} = R_{\hat{\theta}\hat{\theta}\hat{\theta}\hat{\theta}} = -R_{\hat{\theta}\hat{r}\hat{\theta}\hat{\theta}} = \frac{GM}{r^3 c^2} = R_{\hat{r}\hat{\phi}\hat{\theta}\hat{\theta}} \\
&= -R_{\hat{r}\hat{\phi}\hat{\theta}\hat{\theta}} = R_{\hat{\phi}\hat{\theta}\hat{\theta}\hat{\theta}} = -R_{\hat{\phi}\hat{r}\hat{\theta}\hat{\theta}}
\end{aligned} \tag{29}$$

Therefore,

$$\begin{aligned}
e^{\hat{\alpha}_{\hat{0}}}(\hat{\xi}^0) &= ((1 + \frac{a_0 \hat{\xi}^1}{c^2}) \cosh(\frac{a_0 \hat{\xi}^0}{c}), \\
&\quad (1 + \frac{a_0 \hat{\xi}^1}{c^2}) \sinh(\frac{a_0 \hat{\xi}^0}{c}), 0, 0) \\
e^{\hat{\alpha}_{\hat{1}}}(\hat{\xi}^0) &= (\sinh(\frac{a_0 \hat{\xi}^0}{c}), \cosh(\frac{a_0 \hat{\xi}^0}{c}), 0, 0) \\
e^{\hat{\alpha}_{\hat{2}}}(\hat{\xi}^0) &= (0, 0, 1, 0), e^{\hat{\alpha}_{\hat{3}}}(\hat{\xi}^0) = (0, 0, 1, 0)
\end{aligned} \tag{30}$$

$$\begin{aligned}
R_{\hat{0}\hat{1}\hat{0}\hat{1}}(\hat{\xi}) &= \frac{2GM}{r^3 c^2} (1 + \frac{a_0 \hat{\xi}^1}{c^2})^2, \\
R_{\hat{0}\hat{2}\hat{0}\hat{2}}(\hat{\xi}) &= R_{\hat{0}\hat{3}\hat{0}\hat{3}}(\hat{\xi}) = -\frac{GM}{r^3 c^2} (1 + \frac{a_0 \hat{\xi}^1}{c^2})^2 \\
R_{\hat{2}\hat{3}\hat{2}\hat{3}}(\hat{\xi}) &= -\frac{2GM}{r^3 c^2}, \\
R_{\hat{1}\hat{2}\hat{1}\hat{2}}(\hat{\xi}) &= R_{\hat{1}\hat{3}\hat{1}\hat{3}}(\hat{\xi}) = \frac{GM}{r^3 c^2}
\end{aligned} \tag{31}$$

Specially, when $t = 0$,

$$\begin{aligned}
R_{\hat{0}\hat{1}\hat{0}\hat{1}}(\hat{\xi}) &= \frac{2GM}{r^3 c^2} (1 + \frac{a_0 \hat{\xi}^1}{c^2})^2 = \frac{2GM}{r^3 c^2} (1 + \frac{a_0 \hat{r}}{c^2})^2 \\
&= \frac{2GM}{r^3 c^2} [1 + \frac{a_0}{c^2} \{ \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln | \sqrt{r} + \sqrt{r - \frac{2GM}{c^2}} | \\
&\quad - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln | \sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}} | \}]^2
\end{aligned}$$

$$\begin{aligned}
u &= \frac{1}{\sqrt{1 - \frac{2GM}{rc^2}}} \frac{dr}{dt} = 0 \rightarrow \\
V &= \frac{d\hat{r}}{d\hat{t}} = \frac{a_0 \hat{t}}{\sqrt{1 + \frac{a_0^2 \hat{t}^2}{c^2}}} = \frac{dr}{dt} \frac{1}{(1 - \frac{2GM}{rc^2})} = 0
\end{aligned} \tag{32}$$

Therefore, if, $t = \hat{t} = \hat{\xi}^0 = 0$, then the theory treats the real situation.

$$\begin{aligned}
\hat{\xi}^1 &= \sqrt{(\hat{r} + \frac{c^2}{a_0})^2 - c^2 \hat{t}^2} - \frac{c^2}{a_0} = \hat{r} \\
d\hat{r} &= \frac{dr}{\sqrt{1 - \frac{2GM}{rc^2}}} \rightarrow \\
\hat{r} &= \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln | \sqrt{r} + \sqrt{r - \frac{2GM}{c^2}} | \\
&\quad - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln | \sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}} | \\
a_0 &= \frac{1}{\sqrt{1 - \frac{2GM}{rc^2}}} \frac{d}{dt} \left(\frac{u}{\sqrt{1 - \frac{2GM}{rc^2} - \frac{u^2}{c^2}}} \right) = \frac{a}{\sqrt{1 - \frac{2GM}{rc^2}}} \\
a &= \frac{d}{dt} \left(\frac{u}{\sqrt{1 - \frac{2GM}{rc^2} - \frac{u^2}{c^2}}} \right)
\end{aligned} \tag{33}$$

This is equal to $-g$, the pure gravity acceleration. In Eqn. (33), r_0 is the location of the stationary accelerated frame.

In the curved space-time, the curvature tensor $R_{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\lambda}}(\hat{\xi})$ of the stationary accelerated frame is

$$\begin{aligned}
&= \frac{2GM}{r^3 c^2} [1 + \frac{1}{c^2} \frac{a}{\sqrt{1 - \frac{2GM}{rc^2}}} \{ \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln |\sqrt{r} + \sqrt{r - \frac{2GM}{c^2}}| \\
&\quad - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln |\sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}}| \}]^2 \\
R_{\hat{\alpha}\hat{\alpha}\hat{\alpha}}(\hat{\xi}) &= R_{\hat{\alpha}\hat{\alpha}\hat{\beta}}(\hat{\xi}) = -\frac{GM}{r^3 c^2} (1 + \frac{a_0 \hat{\xi}^1}{c^2})^2 = -\frac{GM}{r^3 c^2} (1 + \frac{a_0 \hat{r}}{c^2})^2 \\
&= -\frac{GM}{r^3 c^2} [1 + \frac{a_0}{c^2} \{ \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln |\sqrt{r} + \sqrt{r - \frac{2GM}{c^2}}| \\
&\quad - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln |\sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}}| \}]^2 \\
&= -\frac{GM}{r^3 c^2} [1 + \frac{1}{c^2} \frac{a}{\sqrt{1 - \frac{2GM}{rc^2}}} \{ \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln |\sqrt{r} + \sqrt{r - \frac{2GM}{c^2}}| \\
&\quad - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln |\sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}}| \}]^2 \\
R_{\hat{\beta}\hat{\beta}\hat{\beta}}(\hat{\xi}) &= -\frac{2GM}{r^3 c^2}, \quad R_{\hat{\beta}\hat{\beta}\hat{\alpha}}(\hat{\xi}) = R_{\hat{\beta}\hat{\alpha}\hat{\beta}}(\hat{\xi}) = \frac{GM}{r^3 c^2}
\end{aligned} \tag{34}$$

3.2. Case-2

Now, in Eqns. (10), (11) and (12), if one uses $\hat{\xi}^0$

instead of τ and multiply by $\exp(\frac{a_0}{c^2} \hat{\xi}^1)$

$$e^{\hat{\alpha}_0}(\hat{\xi}^0) = \frac{1}{c} \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^0} = (\exp(\frac{a_0}{c^2} \hat{\xi}^1) \cosh(\frac{a_0 \hat{\xi}^0}{c}), \exp(\frac{a_0}{c^2} \hat{\xi}^1) \sinh(\frac{a_0 \hat{\xi}^0}{c}), 0, 0, 0, 0)$$

$$\tag{35}$$

$$e^{\hat{\alpha}_1}(\hat{\xi}^0) = \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^1} = (\exp(\frac{a_0}{c^2} \hat{\xi}^1) \sinh(\frac{a_0 \hat{\xi}^0}{c}), \exp(\frac{a_0}{c^2} \hat{\xi}^1) \cosh(\frac{a_0 \hat{\xi}^0}{c}), 0, 0, 0, 0)$$

$$\tag{36}$$

$$e^{\hat{\alpha}_2}(\hat{\xi}^0) = \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^2} = (0, 0, 1, 0),$$

$$e^{\hat{\alpha}_3}(\hat{\xi}^0) = \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^3} = (0, 0, 1, 0)$$

$$\tag{37}$$

$$\begin{aligned}
d\hat{x}^\alpha &= \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^\mu} d\hat{\xi}^\mu = e^{\hat{\alpha}_0}(\hat{\xi}^0) cd\hat{\xi}^0 + e^{\hat{\alpha}_1}(\hat{\xi}^0) d\hat{\xi}^1 \\
&\quad + e^{\hat{\alpha}_2}(\hat{\xi}^0) d\hat{\xi}^2 + e^{\hat{\alpha}_3}(\hat{\xi}^0) d\hat{\xi}^3
\end{aligned} \tag{38}$$

Hence,

$$\begin{aligned}
cd\hat{t} &= cdt \sqrt{1 - \frac{2GM}{rc^2}} = \exp(\frac{a_0}{c^2} \hat{\xi}^1) \cosh(\frac{a_0 \hat{\xi}^0}{c}) cd\hat{\xi}^0 \\
&\quad + \exp(\frac{a_0}{c^2} \hat{\xi}^1) \sinh(\frac{a_0 \hat{\xi}^0}{c}) d\hat{\xi}^1
\end{aligned}$$

$$\begin{aligned}
d\hat{r} &= \frac{dr}{\sqrt{1 - \frac{2GM}{rc^2}}} = \exp(\frac{a_0}{c^2} \hat{\xi}^1) \sinh(\frac{a_0 \hat{\xi}^0}{c}) cd\hat{\xi}^0 \\
&\quad + \exp(\frac{a_0}{c^2} \hat{\xi}^1) \cosh(\frac{a_0 \hat{\xi}^0}{c}) d\hat{\xi}^1
\end{aligned} \tag{39}$$

$$d\hat{\theta} = d\hat{\xi}^2, \quad d\hat{\phi} = d\hat{\xi}^3$$

$$\begin{aligned}
d\tau^2 &= \left(1 - \frac{2GM}{rc^2}\right) dt^2 \\
&\quad - \frac{1}{c^2} \left[\frac{dr^2}{1 - \frac{2GM}{rc^2}} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \right] \\
&= d\hat{t}^2 - \frac{1}{c^2} [d\hat{r}^2 + d\hat{\theta}^2 + d\hat{\phi}^2] \\
&= \exp(2 \frac{a_0 \hat{\xi}^1}{c^2}) (d\hat{\xi}^0)^2 \\
&\quad - \frac{1}{c^2} [\exp(2 \frac{a_0 \hat{\xi}^1}{c^2}) (d\hat{\xi}^1)^2 + (d\hat{\xi}^2)^2 + (d\hat{\xi}^3)^2]
\end{aligned} \tag{40}$$

The coordinate transformation is

$$\begin{aligned}
\hat{t} &= \frac{c^2}{a_0} \exp\left(\frac{a_0}{c^2} \hat{\xi}^1\right) \sinh\left(\frac{a_0 \hat{\xi}^0}{c}\right), \\
\hat{r} &= \frac{c^2}{a_0} \exp\left(\frac{a_0}{c^2} \hat{\xi}^1\right) \cosh\left(\frac{a_0 \hat{\xi}^0}{c}\right) - \frac{c^2}{a_0}
\end{aligned}$$

$$\hat{\theta} = \hat{\xi}^2, \hat{\phi} = \hat{\xi}^3 \tag{41}$$

The inverse-transformation is

$$\begin{aligned}
\hat{\xi}^0 &= \frac{c}{a_0} \tanh^{-1} \left(\frac{c\hat{t}}{\hat{r} + \frac{c^2}{a_0}} \right), \\
\hat{\xi}^1 &= \frac{c^2}{a_0} \ln \left| \frac{a_0}{c^2} \sqrt{(\hat{r} + \frac{c^2}{a_0})^2 - c^2 \hat{t}^2} \right| \\
\hat{\xi}^2 &= \hat{\theta}, \hat{\xi}^3 = \hat{\phi}
\end{aligned} \tag{42}$$

If we calculate the curvature tensor $R_{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\lambda}}(\hat{\xi})$ as

$$\begin{aligned}
R_{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\lambda}}(\hat{\xi}) &= \frac{\partial \hat{x}^\alpha}{\partial \hat{\xi}^\mu} \frac{\partial \hat{x}^\beta}{\partial \hat{\xi}^\nu} \frac{\partial \hat{x}^\gamma}{\partial \hat{\xi}^\rho} \frac{\partial \hat{x}^\delta}{\partial \hat{\xi}^\lambda} R_{\hat{\alpha}\hat{\beta}\hat{\gamma}\hat{\delta}}(\hat{X}) \\
&= e^{\hat{\alpha}}{}_{\hat{\mu}}(\hat{\xi}^0) e^{\hat{\beta}}{}_{\hat{\nu}}(\hat{\xi}^0) e^{\hat{\gamma}}{}_{\hat{\rho}}(\hat{\xi}^0) e^{\hat{\delta}}{}_{\hat{\lambda}}(\hat{\xi}^0) R_{\hat{\alpha}\hat{\beta}\hat{\gamma}\hat{\delta}}(\hat{X})
\end{aligned} \tag{43}$$

$$R_{\hat{r}\hat{r}\hat{r}\hat{r}} = -R_{\hat{r}\hat{r}\hat{r}\hat{r}} = R_{\hat{r}\hat{r}\hat{r}\hat{r}} = -R_{\hat{r}\hat{r}\hat{r}\hat{r}} = \frac{2GM}{r^3 c^2},$$

$$\begin{aligned}
R_{\hat{i}\hat{\alpha}\hat{\beta}\hat{\theta}} &= -R_{\hat{i}\hat{\theta}\hat{\alpha}\hat{\beta}} = R_{\hat{\alpha}\hat{\beta}\hat{\theta}\hat{i}} = -R_{\hat{\theta}\hat{i}\hat{\alpha}\hat{\beta}} = -\frac{GM}{r^3 c^2} = R_{\hat{i}\hat{\alpha}\hat{\beta}\hat{\theta}} \\
&= -R_{\hat{i}\hat{\phi}\hat{\theta}\hat{\phi}} = R_{\hat{\phi}\hat{\theta}\hat{\phi}\hat{i}} = -R_{\hat{\theta}\hat{i}\hat{\phi}\hat{\phi}} \\
R_{\hat{\theta}\hat{\phi}\hat{\theta}\hat{\phi}} &= -R_{\hat{\theta}\hat{\phi}\hat{\theta}\hat{\phi}} = R_{\hat{\theta}\hat{\phi}\hat{\theta}\hat{\phi}} = -R_{\hat{\theta}\hat{\phi}\hat{\theta}\hat{\phi}} = -\frac{2GM}{r^3 c^2} \\
R_{\hat{r}\hat{\theta}\hat{\theta}\hat{\theta}} &= -R_{\hat{r}\hat{\theta}\hat{\theta}\hat{\theta}} = R_{\hat{\theta}\hat{\theta}\hat{\theta}\hat{r}} = -R_{\hat{\theta}\hat{\theta}\hat{\theta}\hat{r}} = \frac{GM}{r^3 c^2} = R_{\hat{r}\hat{\theta}\hat{\theta}\hat{\theta}} \\
&= -R_{\hat{r}\hat{\phi}\hat{\theta}\hat{\theta}} = R_{\hat{\phi}\hat{\theta}\hat{\theta}\hat{r}} = -R_{\hat{\phi}\hat{\theta}\hat{\theta}\hat{r}}
\end{aligned} \tag{44}$$

Then,

$$\begin{aligned}
e^{\hat{\alpha}}{}_{\hat{0}}(\hat{\xi}^0) &= (\exp(\frac{a_0}{c^2} \hat{\xi}^1)) \cosh(\frac{a_0 \hat{\xi}^0}{c}), \\
&\quad \exp(\frac{a_0}{c^2} \hat{\xi}^1) \sinh(\frac{a_0 \hat{\xi}^0}{c}), 0, 0 \\
e^{\hat{\alpha}}{}_{\hat{1}}(\hat{\xi}^0) &= (\exp(\frac{a_0}{c^2} \hat{\xi}^1)) \sinh(\frac{a_0 \hat{\xi}^0}{c}), \\
&\quad \exp(\frac{a_0}{c^2} \hat{\xi}^1) \cosh(\frac{a_0 \hat{\xi}^0}{c}), 0, 0 \\
e^{\hat{\alpha}}{}_{\hat{2}}(\hat{\xi}^0) &= (0, 0, 1, 0), \quad e^{\hat{\alpha}}{}_{\hat{3}}(\hat{\xi}^0) = (0, 0, 1, 0)
\end{aligned} \tag{45}$$

$$\begin{aligned}
R_{\hat{0}\hat{1}\hat{0}\hat{1}}(\hat{\xi}) &= \frac{2GM}{r^3 c^2} \exp(4 \frac{a_0 \hat{\xi}^1}{c^2}), \\
R_{\hat{0}\hat{2}\hat{0}\hat{2}}(\hat{\xi}) &= R_{\hat{0}\hat{3}\hat{0}\hat{3}}(\hat{\xi}) = -\frac{GM}{r^3 c^2} \exp(2 \frac{a_0 \hat{\xi}^1}{c^2}) \\
R_{\hat{2}\hat{2}\hat{2}\hat{2}}(\hat{\xi}) &= -\frac{2GM}{r^3 c^2}, \\
R_{\hat{1}\hat{2}\hat{1}\hat{2}}(\hat{\xi}) &= R_{\hat{1}\hat{3}\hat{1}\hat{3}}(\hat{\xi}) = \frac{GM}{r^3 c^2} \exp(2 \frac{a_0 \hat{\xi}^1}{c^2})
\end{aligned} \tag{46}$$

As a special case, when $t = 0$, we obtain

$$\begin{aligned}
u &= \frac{1}{\sqrt{1 - \frac{2GM}{rc^2}}} \frac{dr}{dt} = 0 \rightarrow \\
V &= \frac{d\hat{r}}{d\hat{t}} = \frac{a_0 \hat{t}}{\sqrt{1 + \frac{a_0^2 \hat{t}^2}{c^2}}} = \frac{dr}{dt} \frac{1}{(1 - \frac{2GM}{rc^2})} = 0
\end{aligned} \tag{47}$$

Therefore, if $t = \hat{t} = \hat{\xi}^0 = 0$, the theory treats the real situation.

$$\begin{aligned}
\hat{\xi}^1 &= \frac{c^2}{a_0} \ln \left| \frac{a_0}{c^2} \sqrt{\left(\hat{r} + \frac{c^2}{a_0}\right)^2 - c^2 \hat{t}^2} \right| = \frac{c^2}{a_0} \ln \left| \left(1 + \frac{a_0}{c^2} \hat{r}\right) \right| \\
\exp\left(\frac{a_0}{c^2} \hat{\xi}^1\right) &= 1 + \frac{a_0}{c^2} \hat{r} \\
d\hat{r} &= \frac{dr}{\sqrt{1 - \frac{2GM}{rc^2}}} \rightarrow \hat{r} = \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln \left| \sqrt{r} + \sqrt{r - \frac{2GM}{c^2}} \right| \\
&\quad - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln \left| \sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}} \right| \\
a_0 &= \frac{1}{\sqrt{1 - \frac{2GM}{rc^2}}} \frac{d}{dt} \left(\frac{u}{\sqrt{1 - \frac{2GM}{rc^2} - \frac{u^2}{c^2}}} \right) = \frac{a}{\sqrt{1 - \frac{2GM}{rc^2}}} \\
a &= \frac{d}{dt} \left(\frac{u}{\sqrt{1 - \frac{2GM}{rc^2} - \frac{u^2}{c^2}}} \right)
\end{aligned} \tag{48}$$

Now, in the curved space-time, the curvature tensor $R_{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\lambda}}(\hat{\xi})$ of the stationary accelerated frame is

$$\begin{aligned}
R_{\hat{0}\hat{1}\hat{0}\hat{1}}(\hat{\xi}) &= \frac{2GM}{r^3 c^2} \exp\left(4 \frac{a_0 \hat{\xi}^1}{c^2}\right) = \frac{2GM}{r^3 c^2} \left(1 + \frac{a_0}{c^2} \hat{r}\right)^4 \\
&= \frac{2GM}{r^3 c^2} \left[1 + \frac{a_0}{c^2} \left\{ \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln \left| \sqrt{r} + \sqrt{r - \frac{2GM}{c^2}} \right| \right. \right. \\
&\quad \left. \left. - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln \left| \sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}} \right| \right\} \right]^4 \\
&= \frac{2GM}{r^3 c^2} \left[1 + \frac{1}{c^2} \frac{a}{\sqrt{1 - \frac{2GM}{rc^2}}} \left\{ \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln \left| \sqrt{r} + \sqrt{r - \frac{2GM}{c^2}} \right| \right. \right. \\
&\quad \left. \left. - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln \left| \sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}} \right| \right\} \right]^4 \\
R_{\hat{0}\hat{2}\hat{0}\hat{2}}(\hat{\xi}) &= R_{\hat{0}\hat{3}\hat{0}\hat{3}}(\hat{\xi}) = -\frac{GM}{r^3 c^2} \exp\left(2 \frac{a_0 \hat{\xi}^1}{c^2}\right) = -\frac{GM}{r^3 c^2} \left(1 + \frac{a_0}{c^2} \hat{r}\right)^2 \\
&= -\frac{GM}{r^3 c^2} \left[1 + \frac{a_0}{c^2} \left\{ \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln \left| \sqrt{r} + \sqrt{r - \frac{2GM}{c^2}} \right| \right. \right. \\
&\quad \left. \left. - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln \left| \sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}} \right| \right\} \right]^2 \\
&= -\frac{GM}{r^3 c^2} \left[1 + \frac{1}{c^2} \frac{a}{\sqrt{1 - \frac{2GM}{rc^2}}} \left\{ \sqrt{r} \sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2} \ln \left| \sqrt{r} + \sqrt{r - \frac{2GM}{c^2}} \right| \right. \right. \\
&\quad \left. \left. - \sqrt{r_0} \sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2} \ln \left| \sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}} \right| \right\} \right]^2
\end{aligned}$$

$$\begin{aligned}
R_{\hat{2}\hat{3}\hat{2}\hat{3}}(\hat{\xi}) &= -\frac{2GM}{r^3c^2}, \\
R_{\hat{1}\hat{2}\hat{1}\hat{2}}(\hat{\xi}) = R_{\hat{1}\hat{3}\hat{1}\hat{3}}(\hat{\xi}) &= \frac{GM}{r^3c^2} \exp(2\frac{a_0}{c^2}\hat{\xi}^1) = \frac{GM}{r^3c^2}(1 + \frac{a_0}{c^2}\hat{r})^2 \\
&= \frac{GM}{r^3c^2}[1 + \frac{a_0}{c^2}\{\sqrt{r}\sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2}\ln|\sqrt{r} + \sqrt{r - \frac{2GM}{c^2}}| \\
&\quad - \sqrt{r_0}\sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2}\ln|\sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}}|\}]^2 \\
&= \frac{GM}{r^3c^2}[1 + \frac{1}{c^2}\frac{a}{\sqrt{1 - \frac{2GM}{rc^2}}}\{\sqrt{r}\sqrt{r - \frac{2GM}{c^2}} + \frac{2GM}{c^2}\ln|\sqrt{r} + \sqrt{r - \frac{2GM}{c^2}}| \\
&\quad - \sqrt{r_0}\sqrt{r_0 - \frac{2GM}{c^2}} - \frac{2GM}{c^2}\ln|\sqrt{r_0} + \sqrt{r_0 - \frac{2GM}{c^2}}|\}]^2
\end{aligned} \tag{49}$$

4. Conclusion

In the general relativity theory, we define the accelerated frame that moves in \hat{r} -axis in the curved time-space. Specially, if, $t = \hat{t} = \hat{\xi}^0 = 0$, this theory treats the curvature tensor of the stationary accelerated frame in the curved space-time in two-cases. In this context, the curvature tensor is divided into two parts: $R_{\hat{\mu}\hat{\nu}\hat{\rho}\hat{\lambda}}(\hat{\xi})$ is the curvature tensor as observed by the observer and $R_{\hat{\alpha}\hat{\beta}\hat{\gamma}\hat{\delta}}(\hat{X})$ is the curvature tensor of the observer's own planet in the gravity field.

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